

- determine where a variable might point (refer) to

why?

- optimization
- bug detection and security
- software understanding

⇒ mostly as a service to other program analysis

⇒ fundamental topic in program analysis

program

```
X: a = new Object();  
Y: b = new Object();  
Z: c = new Object();  
  a = b;  
  b = a;  
  c = b;
```

facts

```
AssignHeapAllocation("a", "X").  
AssignHeapAllocation("b", "Y").  
AssignHeapAllocation("c", "Z").  
AssignLocal("b", "a").  
AssignLocal("a", "b").  
AssignLocal("b", "c").
```

program

```
X: a = new Object();
Y: b = new Object();
Z: c = new Object();
   a = b;
   b = a;
   c = b;
```

```
AssignHeapAllocation(?heap, ?to) ->
HeapAllocationRef(?heap),
VarRef(?to).
```

facts

```
AssignHeapAllocation("a", "X").
AssignHeapAllocation("b", "Y").
AssignHeapAllocation("c", "Z").
AssignLocal("b", "a").
AssignLocal("a", "b").
AssignLocal("b", "c").
```

```
AssignLocal(?from, ?to) ->
VarRef(?from),
VarRef(?to).
```

datalog

```
VarPointsTo(?var, ?heap) <-  
  AssignHeapAllocation(?heap, ?var).
```

```
VarPointsTo(?to, ?heap) <-  
  AssignLocal(?from, ?to),  
  VarPointsTo(?from, ?heap).
```

query

```
?- VarPointsTo(?var, ?heap).  
  ("a", "X") ("a", "Y")  
  ("b", "X") ("b", "Y")  
  ("c", "X") ("c", "Y") ("c", "Z")
```

```
void main() {  
  X: a = new Object();  
    b = f(a);  
}
```

```
void f(Object o) {  
  return o;  
}
```

```
FormalParam["f", 0] = "o".  
ReturnVar("f", "o").
```

```
AssignHeapAllocation("a", "X").  
CallGraphEdge("main/f", "f").  
ActualParam["main/f", 0] = "a".  
AssignReturnValue("main/f", "b").
```

```
void main() {  
  X: a = new Object();  
    b = f(a);  
}  
  
void f(Object o) {  
  return o;  
}
```

```
FormalParam[?method, ?index] = ?var ->  
  MethodDeclarationRef(?method),  
  ParamIndexRef(?index),  
  VarRef(?var).
```

```
FormalParam["f", 0] = "o".  
ReturnVar("f", "o").  
  
AssignHeapAllocation("a", "X").  
CallGraphEdge("main/f", "f").  
ActualParam["main/f", 0] = "a".  
AssignReturnValue("main/f", "b").
```

```
void main() {  
  X: a = new Object();  
    b = f(a);  
}  
  
void f(Object o) {  
  return o;  
}
```

```
ReturnVar(?method, ?var) ->  
MethodDeclarationRef(?method),  
VarRef(?var).
```

```
FormalParam["f", 0] = "o".  
ReturnVar("f", "o").  
  
AssignHeapAllocation("a", "X").  
CallGraphEdge("main/f", "f").  
ActualParam["main/f", 0] = "a".  
AssignReturnValue("main/f", "b").
```

```
void main() {  
  X: a = new Object();  
    b = f(a);  
}
```

```
void f(Object o) {  
  return o;  
}
```

```
CallGraphEdge(?invocation, ?method) ->  
  MethodInvocationRef(?invocation),  
  MethodDeclarationRef(?method).
```

```
FormalParam["f", 0] = "o".  
ReturnVar("f", "o").
```

```
AssignHeapAllocation("a", "X").  
CallGraphEdge("main/f", "f").  
ActualParam["main/f", 0] = "a".  
AssignReturnValue("main/f", "b").
```



```
void main() {  
  X: a = new Object();  
    b = f(a);  
}
```

```
void f(Object o) {  
  return o;  
}
```

```
ActualParam[?invocation, ?index] = ?var ->  
  MethodInvocationRef(?invocation),  
  ParamIndexRef(?index),  
  VarRef(?var).
```

```
FormalParam["f", 0] = "o".  
ReturnVar("f", "o").
```

```
AssignHeapAllocation("a", "X").  
CallGraphEdge("main/f", "f").  
ActualParam["main/f", 0] = "a".  
AssignReturnValue("main/f", "b").
```

```
void main() {  
  X: a = new Object();  
    b = f(a);  
}
```

```
void f(Object o) {  
  return o;  
}
```

```
AssignReturnValue(?invocation, ?to) ->  
  MethodInvocationRef(?invocation),  
  VarRef(?to).
```

```
FormalParam["f", 0] = "o".  
ReturnVar("f", "o").
```

```
AssignHeapAllocation("a", "X").  
CallGraphEdge("main/f", "f").  
ActualParam["main/f", 0] = "a".  
AssignReturnValue("main/f", "b").
```

```
VarPointsTo(?var, ?heap) <-  
  AssignHeapAllocation(?heap, ?var).
```

```
VarPointsTo(?to, ?heap) <-  
  Assign(?from, ?to), VarPointsTo(?from, ?heap).
```

```
Assign(?from, ?to) <- AssignLocal(?from, ?to).
```

```
Assign(?actual, ?formal) <-  
  FormalParam[?method, ?index] = ?formal,  
  ActualParam[?invocation, ?index] = ?actual,  
  CallGraphEdge(?invocation, ?method).
```

```
Assign(?return, ?local) <-  
  ReturnVar(?method, ?return),  
  CallGraphEdge(?invocation, ?method),  
  AssignReturnValue(?invocation, ?local).
```

program

```
void main() {  
  X: a = new Object();  
    b = f(a);  
}  
  
void f(Object o) {  
  return o;  
}
```

points-to information

```
?- VarPointsTo(?var, ?heap).  
  ("a", "X")  
  ("o", "X")  
  ("b", "X")
```

- directionality
- flow sensitivity
- call graph precision
- reachability [skip]
- context sensitivity
- heap abstraction
- field abstraction [skip]

subset constraints

- $a = b \rightarrow \text{VarPointsTo}("b") \subseteq \text{VarPointsTo}("a")$

```
VarPointsTo(?to, ?heap) <-  
  Assign(?from, ?to), VarPointsTo(?from, ?heap).
```

equivalence constraint

- $a = b \rightarrow \text{VarPointsTo}("a") = \text{VarPointsTo}("b")$

```
VarPointsTo(?to, ?heap) <-  
  Assign(?from, ?to), VarPointsTo(?from, ?heap).
```

```
VarPointsTo(from, ?heap) <-  
  Assign(?from, ?to), VarPointsTo(?to, ?heap).
```

```
X: a = new Object();  
   b = a;  
Y: a = new Object();
```

```
AssignHeapAllocation("a", "X").  
AssignHeapAllocation("a", "Y").  
AssignLocal("a", "b").
```

```
?- VarPointsTo(?var, ?heap).  
   ("a", "X") ("a", "Y") ("b", "X") ("b", "Y")
```

- flow-sensitive analysis is unpopular
- most of the benefits can be achieved with SSA

```
void main() {
    Base a = new Extension1();
    a.f();
    Base b = new Extension2();
    b.f();
}

class Base {
    void f() {}
}

class Extension1 extends Base {
    void f() {}
}

class Extension2 extends Base {
}
```


pre-computed

- CHA
- RTA
- imprecise pointer analysis (e.g. Whaley)

```
CallGraphEdge("main.f1", "Base.f").  
CallGraphEdge("main.f1", "Extension1.f").  
CallGraphEdge("main.f1", "Extension2.f").
```

```
CallGraphEdge("main.f2", "Base.f").  
CallGraphEdge("main.f2", "Extension1.f").  
CallGraphEdge("main.f2", "Extension2.f").
```

better: **on-the-fly** using virtual method resolution

```
AssignHeapAllocation("a", "new Extension1").
AssignHeapAllocation("b", "new Extension2").

HeapAllocation("new Extension1", "Extension1").
HeapAllocation("new Extension2", "Extension2").

VirtualMethodInvocation("main.f1", "a", "<Base: void f()>").
VirtualMethodInvocation("main.f2", "b", "<Base: void f()>").

MethodSignature("<Base: void f()>", "Base", "f", "void()").
MethodSignature("<Extension1: void f()>", "Extension1", "f", "void()").

MethodDeclaration["<Base: void f()>"] = "Base.f".
MethodDeclaration["<Extension1: void f()>"] = "Extension1.f".

SuperType("Base", "java.lang.Object").
SuperType("Extension1", "Base").
SuperType("Extension2", "Base").
```

```
AssignM VirtualMethodInvocation(?invocation, ?base, ?sig) ->  
AssignM MethodInvocationRef(?invocation),  
HeapAll VarRef(?base),  
HeapAll MethodSignatureRef(?sig).
```

```
VirtualMethodInvocation("main.f1", "a", "<Base: void f()>").
```

```
VirtualMethodInvocation("main.f2", "b", "<Base: void f()>").
```

```
MethodSignature("<Base: void f()>", "Base", "f", "void()").
```

```
MethodSignature("<Extension1: void f()>", "Extension1", "f", "void()").
```

```
MethodDeclaration["<Base: void f()>"] = "Base.f".
```

```
MethodDeclaration["<Extension1: void f()>"] = "Extension1.f".
```

```
SuperType("Base", "java.lang.Object").
```

```
SuperType("Extension1", "Base").
```

```
SuperType("Extension2", "Base").
```

```
AssignHeapAllocation("a", "new Extension1").
AssignHeapAllocation("b", "new Extension2").

HeapAllocation("new Extension1", "Extension1").
HeapAllocation("new Extension2", "Extension2").

VirtualMethodInvocation("main.f1", "a", "<Base: void f()>").
VirtualMethodInvocation("main.f2", "b", "<Base: void f()>").

MethodSignature("<Base: void f()>", "Base", "f", "void()").
MethodSignature("<Extension1: void f()>", "Extension1", "f", "void()")
```

```
MethodSignature(?ref, ?type, ?simplename, ?descriptor) ->
MethodSignatureRef(?ref),
TypeRef(?type),
SimpleNameRef(?simplename),
MethodDescriptorRef(?descriptor).
```

```
AssignHeapAllocation("a", "new Extension1").
AssignHeapAllocation("b", "new Extension2").
```

```
HeapAllocation("new Extension1", "Extension1").
HeapAllocation("new Extension2", "Extension2").
```

```
VirtualMethodInvocation("main.f1", "a", "<Base: void f()>").
VirtualMethodInvocation("main.f2", "b", "<Base: void f()>").
```

```
MethodSignature("<Base: void f()>", "Base", "f", "void()").
MethodSignature("<Extension1: void f()>", "Extension1", "f", "void()")
```

```
MethodDeclaration["<Base: void f()>"] = "Base.f".
MethodDeclaration["<Extension1: void f()>"] = "Extension1.f".
```

```
SuperType("Base", "java.lang.Object", MethodDeclaration[?signature] = ?ref ->
SuperType("Extension1", "Base", MethodSignatureRef(?signature),
SuperType("Extension2", "Base", MethodDeclarationRef(?ref)).
```

```

AssignHeapAllocation("a", "new Extension1").
AssignHeapAllocation("b", "new Extension2").

HeapAllocation("new Extension1", "Extension1").
HeapAllocation("new Extension2", "Extension2").

VirtualMethodInvocation("main.f1", "a", "<Base: void f()>").
VirtualMethodInvocation("main.f2", "b", "<Base: void f()>").

MethodSignature("<Base: void f()>", "Base", "f", "void()").
MethodSignature("<Extension1: void f()>", "Extension1", "f", "void()").

MethodDeclaration["<Base: void f()>"]
MethodDeclaration["<Extension1: void f()>"]

SuperType["Base", "java.lang.Object"].
SuperType["Extension1", "Base"].
SuperType["Extension2", "Base"].

```

```

SuperType[?ref] = ?super ->
  TypeRef(?ref),
  TypeRef(?super).

```

virtual method resolution

```
ResolveMethod[?type, ?simplename, ?descriptor] = ?method <-  
  MethodDeclared[?type, ?simplename, ?descriptor] = ?method.
```

```
ResolveMethod[?type, ?simplename, ?descriptor] = ?method <-  
  SuperType[?type] = ?supertype,  
  ResolveMethod[?supertype, ?simplename, ?descriptor] = ?method,  
  not MethodDeclared[?type, ?simplename, ?descriptor] = _.
```

```
MethodDeclared[?type, ?simplename, ?descriptor] = ?method <-  
  MethodSignature(?signature, ?type, ?simplename, ?descriptor),  
  MethodDeclaration[?signature] = ?method.
```

virtual method resolution

```
CallGraphEdge(?invocation, ?tomethod) <-  
  VirtualMethodInvocation(?invocation, ?base, ?signature),  
  VarPointsTo(?base, ?heap),  
  HeapAllocation(?heap, ?type),  
  MethodSignature(?signature, _, ?simplename, ?descriptor),  
  ResolveMethod[?type, ?simplename, ?descriptor] = ?tomethod.
```

```
CallGraphEdge(?invocation, ?method) <-  
  StaticMethodInvocation(_, ?invocation, ?sig),  
  MethodDeclaration[?sig] = ?method.
```



```
void main() {
    Base a = new Extension1();
    a.f();
    Base b = new Extension2();
    b.f();
}

class Base {
    void f() {}
}

class Extension1 extends Base {
    void f() {}
}

class Extension2 extends Base {
}
```

```
?- ResolveMethod(?type, ?name, ?descriptor) = ?method.  
void m ('Base', 'f', 'void()', 'Base.f')  
  Base ('Extension1', 'f', 'void()', 'Extension1.f')  
  a.f ('Extension2', 'f', 'void()', 'Base.f')  
  Base  
  b.f (?- CallGraphEdge(?inv, ?m).  
} ('main.f1', 'Extension1.f')  
 ('main.f2', 'Base.f')  
  
class Base {  
  void f() {}  
}  
  
class Extension1 extends Base {  
  void f() {}  
}  
  
class Extension2 extends Base {  
}
```

```
void main () {  
  X: a = new Object();  
  Y: b = new Object();  
    c = identity(a);  
    d = identity(b);  
}  
Object identity(Object o) { return o; }
```

```
CallGraphEdge("main/identity1", "identity").  
CallGraphEdge("main/identity2", "identity").  
ActualParam["main/identity1", 0] = "a".  
ActualParam["main/identity2", 0] = "b".  
AssignReturnValue("main/identity1", "c").  
AssignReturnValue("main/identity2", "d").  
FormalParam["identity", 0] = "o".  
ReturnVar("identity", "o").
```

```
void main () {  
  X: a = new Object();  
  Y: b = new Object();  
    c = identity(a);  
    d = identity(b);  
}  
Object identity(Object o) { return o; }
```

```
CallGraphEdge("main/identity1", "identity").  
CallGraphEdge("main/identity2", "identity").  
ActualParam["main/identity1", 0] = "a".  
ActualParam["main/identity2", 0] = "b".  
AssignReturnValue("main/identity1", "c").  
AssignReturnValue("main/identity2", "d").  
FormalParam["identity", 0] = "o".  
ReturnVar("identity", "o").
```

("a", "X")

("b", "Y")

("o", "X")

("o", "Y")

("c", "X")

("c", "Y")

("d", "X")

("d", "Y")

- analyse a method for multiple contexts
- context: static abstraction of a set of run-time invocations
- examples:
 - call-site
 - series of call-sites (1, 2, ..., acyclic, ∞)
 - target object
 - series of target objects
 - types of parameters
- main source of complexity
- flurry of research last decade
- not really shown to scale, in particular in combination with other essential features.

context-insensitive

```
VarPointsTo(?var, ?heap) <-  
  AssignHeapAllocation(_, ?heap, ?var).
```

context-sensitive

```
VarPointsTo(?ctx, ?var, ?heap) <-  
  AssignHeapAllocation(?inmethod, ?heap, ?var),  
  Reachable(?ctx, ?inmethod).
```

new facts

```
AssignHeapAllocation("main", "a", "X").  
AssignHeapAllocation("main", "b", "Y").
```

context-insensitive call graph

```
CallGraphEdge(?invocation, ?method)
```

context-sensitive call graph

```
CallGraphEdge(?callerCtx, ?invocation, ?invocation, ?tomethod) <-  
  VirtualMethodInvocation(?inmethod, ?invocation, ?base, ?signature),  
  Reachable(?callerCtx, ?inmethod),  
  VarPointsTo(?callerCtx, ?base, ?heap),  
  HeapAllocation(?heap, ?type),  
  MethodSignature(?signature, _, ?simplename, ?descriptor),  
  ResolveMethod[?type, ?simplename, ?descriptor] = ?tomethod.
```

new facts

```
MethodInvocation("main/identity1", "main", "@this", "identity").  
MethodInvocation("main/identity2", "main", "@this", "identity").
```

reachability

```
Reachable(ctx, ?method) <-  
  MethodInvocationRef(ctx),  
  MethodInvocationRef:Value(ctx:"<<initial-context>>"),  
  MainMethodDeclaration(?method).  
  
Reachable(?ctx, ?method) <-  
  CallGraphEdge(_, _, ?ctx, ?method).  
  
MainMethodDeclaration(?method) <-  
  MethodSignature(?signature, _, simplename, descriptor),  
  SimpleNameRef:Value(simplename:"main"),  
  MethodDescriptorRef:Value(descriptor:"void(java.lang.String[])"),  
  MethodDeclaration[?signature] = ?method.
```


assignments become context-specific

```
Assign(?callerCtx, ?base, ?calleeCtx, ?this) <-  
  ThisVar[?method] = ?this,  
  CallGraphEdge(?callerCtx, ?invocation, ?calleeCtx, ?method),  
  Base[?invocation] = ?base.
```

```
Assign(?callerCtx, ?actual, ?calleeCtx, ?formal) <-  
  FormalParam[?method, ?index] = ?formal,  
  ActualParam[?invocation, ?index] = ?actual,  
  CallGraphEdge(?callerCtx, ?invocation, ?calleeCtx, ?method).
```

```
VarPointsTo(?toCtx, ?to, ?h) <-  
  Assign(?fromCtx, ?from, ?toCtx, ?to),  
  VarPointsTo(?fromCtx, ?from, ?h).
```

```
void main () {  
  X: a = new Object();  
  Y: b = new Object();  
    c = identity(a);  
    d = identity(b);  
}
```

```
Object identity(Object o) { return o; }
```

```
?- VarPointsTo(?ctx, ?var, ?heap).  
  ("<<initial-context>>", "a", "X")  
  ("<<initial-context>>", "b", "Y")  
  ("<<initial-context>>", "c", "X")  
  ("<<initial-context>>", "d", "Y")  
  ("main/identity1", "o", "X")  
  ("main/identity2", "o", "Y")
```

how to represent an heap allocation?

```
void main() {  
    a = allocate();  
    b = allocate();  
}  
  
Object allocate() {  
    X: o = new Object();  
    return o;  
}
```

- common in recent frameworks, libraries
- solution: context-sensitive heap abstraction
 - a.k.a. heap cloning
 - a.k.a. heap specialization

context-insensitive heap abstraction

```
VarPointsTo(?ctx, ?var, ?heap) :-  
  AssignHeapAllocation(?inmethod, ?var, ?heap),  
  Reachable(?ctx, ?inmethod).
```

context-sensitive heap abstraction

```
VarPointsTo(?ctx, ?var, Heap(?ctx, ?heap)) :-  
  AssignHeapAllocation(?inmethod, ?var, ?heap),  
  Reachable(?ctx, ?inmethod).
```

```
void main() {  
  a = allocate();  
  b = allocate();  
}
```

```
Object allocate() {  
  X: o = new Object();  
  return o;  
}
```

```
?- VarPointsTo(?ctx, ?var, ?heap).  
  ("main/allocate1", "o", Heap("main/allocate1", "X"))  
  ("main/allocate2", "o", Heap("main/allocate2", "X"))  
  ("initial-context", "a", Heap("main/allocate1", "X"))  
  ("initial-context", "b", Heap("main/allocate2", "X"))
```

```
InstanceFieldPointsTo(?baseheap, ?sig, ?heap) <-  
  StoreInstanceField(?inmethod, ?from, ?base, ?sig),  
  Reachable(?ctx, ?inmethod),  
  VarPointsTo(?ctx, ?from, ?heap),  
  VarPointsTo(?ctx, ?base, ?baseheap).
```

```
VarPointsTo(?ctx, ?to, ?heap) <-  
  LoadInstanceField(?inmethod, ?base, ?sig, ?to),  
  Reachable(?ctx, ?inmethod),  
  VarPointsTo(?ctx, ?base, ?baseheap),  
  InstanceFieldPointsTo(?baseheap, ?sig, ?heap).
```

pointer analysis that is:

- scalable (millions lines of code)
- fast in absolute time (seconds)

nobody has succeeded at creating an algorithm that supports:

- inclusion constraints
- on-the-fly call graph construction
- context-sensitive analysis
- context-sensitive heap abstraction

all current publications sacrifice at one, or usually more, points